

REeal data AnaLysis GOCE

Gravity field determination from GOCE

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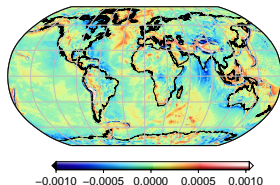
⁴ Graz University of Technology (now)

BMBF Geotechnologien Statusseminar:
„Erfassung des Systems Erde aus dem Weltraum III“

Potsdam, 24/05/2012

Aim:

Determination of a gravity field with high accuracy and resolution.



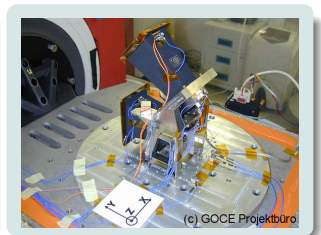
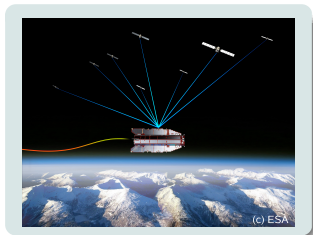
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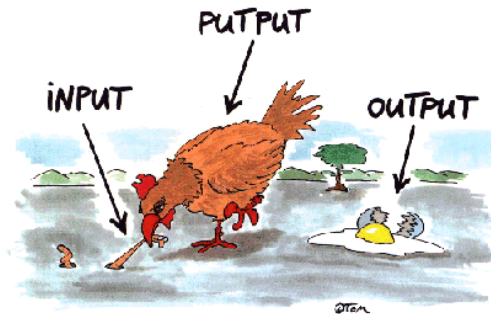
Sensors for gravity field determination:

GPS tracking (SST)

Gradiometry (SGG)

star tracker (STR)





Input:
GOCE observations

Putput:
Gravity field analysis

Output:
Gravity coefficients
+ accuracies

GOCE observations:

gravity gradients



orbit + accuracies



orientation



Satellite-gravity-gradiometry (SGG) observations:

- ▶ calibrated gravity gradients $V_{ij}, i, j \in \{x, y, z\}$
- ▶ source: ESA HPF/EGG-C

Satellite-to-Satellite tracking (SST) observations:

- ▶ kinematic precise orbits (GPS Code/Phase observations)
- ▶ source: ESA HPF/EGG-C or REAL GOCE (IGG-APMG)

Available SGG Data:



- ▶ increasing number of data:
~ 2, 6, 12 months
- ▶ sampling rate: 1 sec.

Problems:

- ▶ number of observations: 30 Mio. per component
 - ⇒ required memory:
e.g. $A \sim 15$ Terabyte
 - ⇒ time-consuming estimation:
~ 1000 Tage

Observation equation

$$\ell_{[30 \text{ Mio.} \times 1]} + v = A_{[30 \text{ Mio.} \times 63.000]} x$$

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Solutions:

- ▶ tailored algorithms
- ▶ iterative, massive parallel software
- ▶ computation on supercomputers
- ▶ downsampling (e.g. IGG-APMG: 5 sec.)



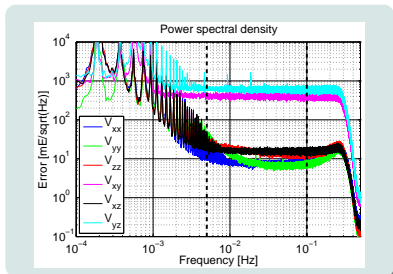
(c) FZ Jülich

Spectral characteristics of SGG noise:

- ▶ observations per component are highly correlated
- ▶ two gradient components with very high noise levels (V_{xy} , V_{yz})

Problems:

- ▶ covariance matrix is fully occupied
- ▶ memory requirements per component: 7 PetaByte



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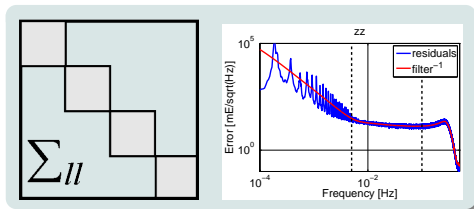
Stochastic model

$$\Sigma\{\mathcal{L}\} = \Sigma_{[30 \text{ Mio.} \times 30 \text{ Mio.}]}$$

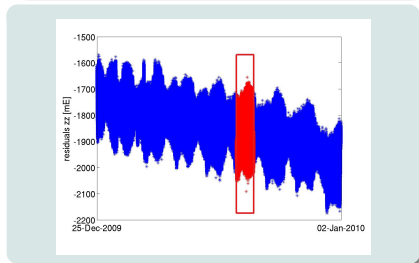
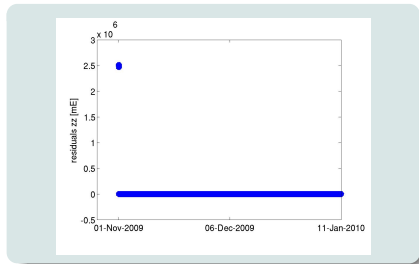
Solutions:

Decorrelation with ...

- ▶ digital, discrete filters
- ▶ empirical covariance matrix for data segments, independence of segments



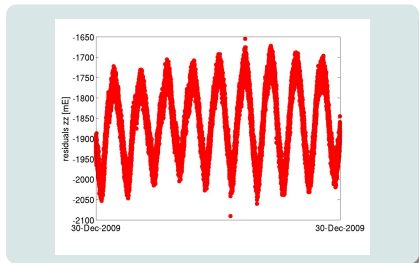
Local characteristics of SGG data: Outliers



Problems:

- ▶ noise has a high amplitude and a trend
 - ⇒ outliers not obviously
 - ⇒ automatic search not possible
- ▶ robust least squares solution require a datenscreening

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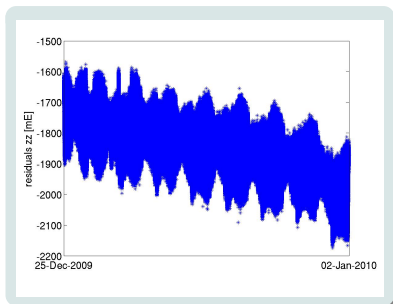


Local characteristics of SGG data: Outliers

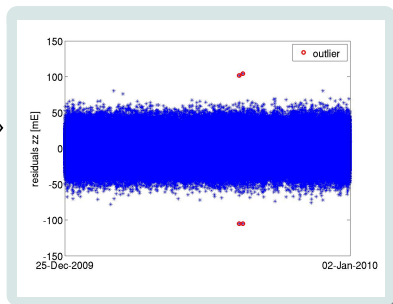
Solution:

- ▶ filtering with a high-pass filter (e.g. differentiation filter):
 - ▶ elimination of the trend
 - ▶ outliers are visible \implies automatic search possible
 - ▶ temporal changes are visible

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filtering \rightarrow

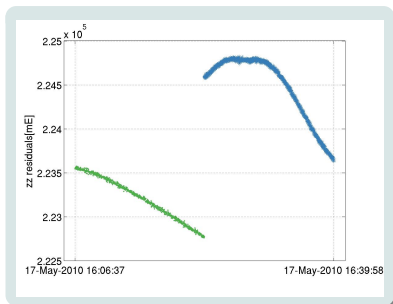


Local characteristics of SGG data: Outliers

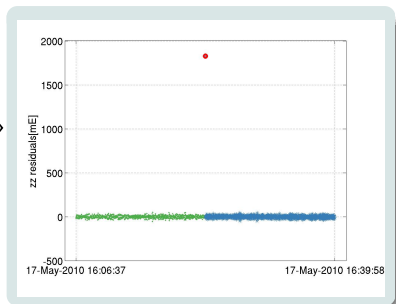
Solution:

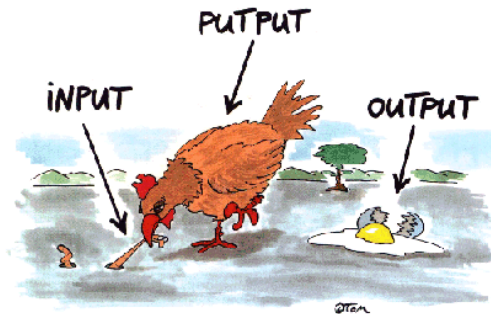
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filtering \rightarrow





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Gravity coefficients
+ accuracies

SGG - deterministic model:

1. Invariants Approach (GIS):

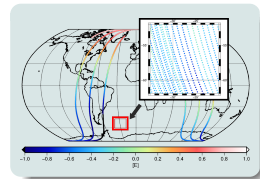
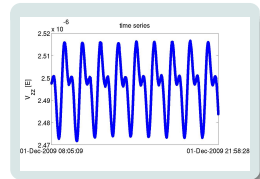
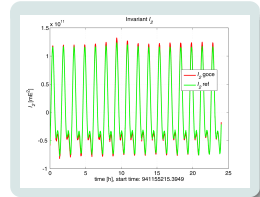
- ▶ rotational invariants of the gradient tensor
- e.g. $I_2 = \frac{1}{2}(V_{xx}^2 + V_{yy}^2 + V_{zz}^2) - V_{xy}^2 - V_{xz}^2 - V_{yz}^2$
- ▶ invariants as equidistant, gap-less time-series
- ▶ global representation

2. Time-Wise Approach (IGG-TG):

- ▶ V_{xx}, V_{yy}, V_{zz} as 2nd derivative of potential in GRF
- ▶ gradients as equidistant, gap-less time-series
- ▶ global representation

3. Short-Arc Approach (IGG-APMG):

- ▶ V_{xx}, V_{yy}, V_{zz} as 2nd derivative of potential in GRF
- ▶ analysis of short arcs (~ 15 min.) with 5 sec. sampling
- ▶ global and local representation



SGG - stochastic model:

1. Invariants Approach (GIS):

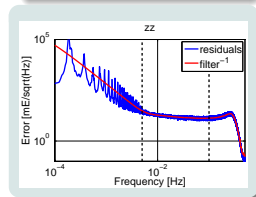
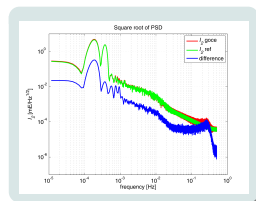
- ▶ decorrelation by digital MA filter cascades
- ▶ filters are adjusted to invariants

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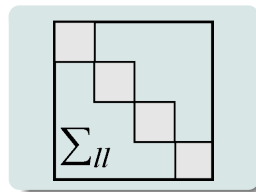
- ▶ decorrelation by digital ARMA filter cascades
- ▶ filters are adjusted to gradients

3. Short-Arc Approach (IGG-APMG):

- ▶ full variance covariance information per short arc
- ▶ arcs are independent
- ▶ arc-wise reweighting of observations



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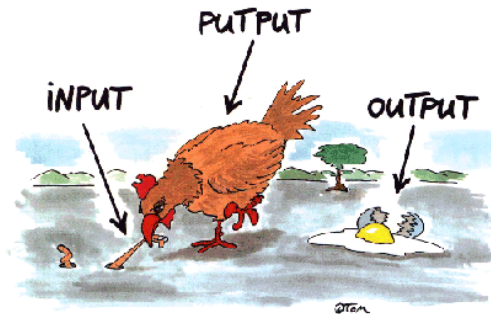
Cooperations within the gravity field processing groups:

- ▶ **IGG-TG** \implies **GIS**: filter adjustment by invariants
- ▶ **IGG-TG** \iff **IGG-APMG**: stochastic model analysis, filter vs. covariance function per arcs
- ▶ **ALL** \implies **ALL**: outlier information, quality information on gradients
- ▶ **ALL** \implies **ALL**: validation of results

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Cooperations with other groups within REAL GOCE:

- ▶ **IGG-APMG** \implies **WP 150 (KIT)**: use of topographic-isostatic reduction of GOCE gravity gradients
- ▶ **IGG-APMG/IGG-TG** \implies **WP 310 (BKG)** : validation of gravity fields
- ▶ **IGG-TG** \implies **WP 110 (IAPG/DGFI)**: validation of reprocessed SGG data
- ▶ **All** \implies **WP 220 (IFM)** : application of gravity models to ocean circulation studies



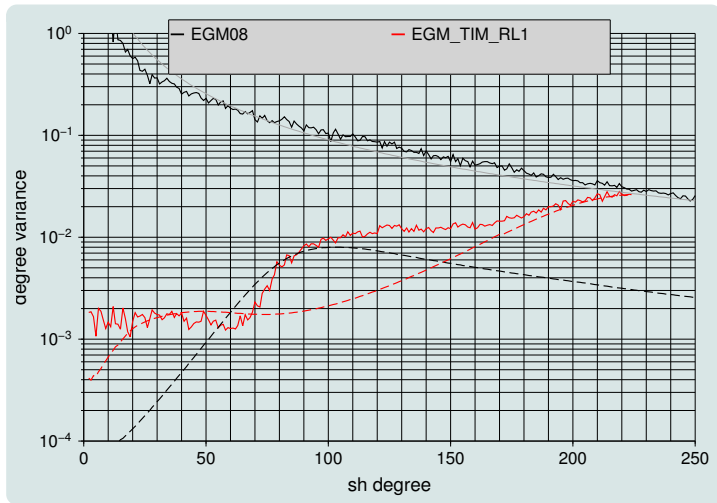
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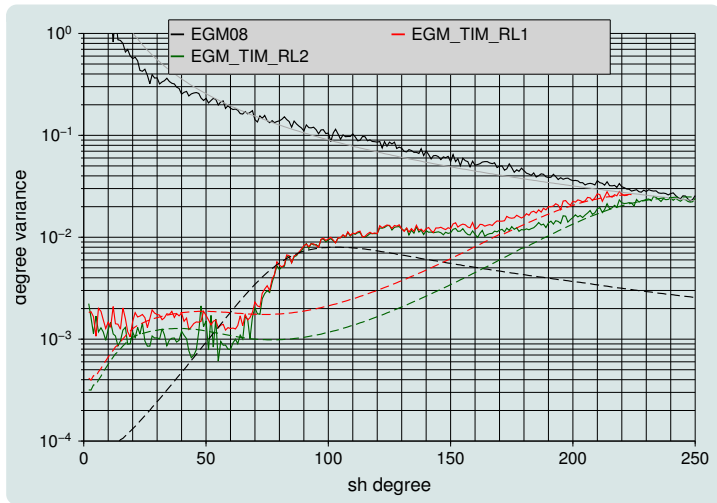
GOCE-only models compared to EGM08: 2

months data



solid: degree error variance from difference to EGM08, **dashed:** degree error variance from formal errors

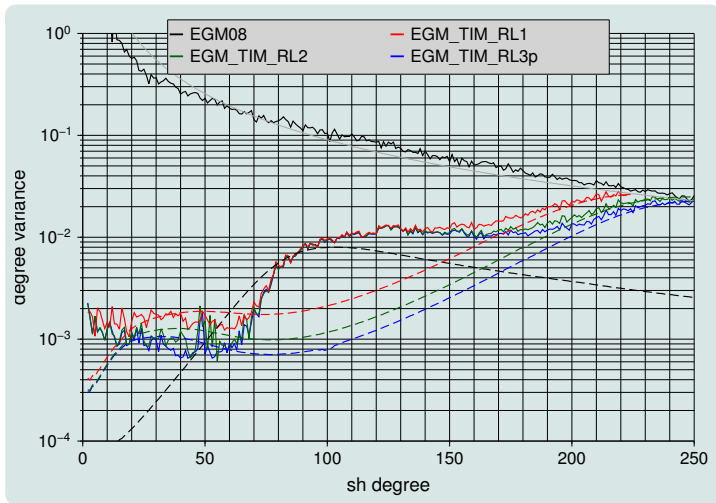
GOCE-only models compared to EGM08: 2, 6 months data



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solid: degree error variance from difference to EGM08, **dashed:** degree error variance from formal errors

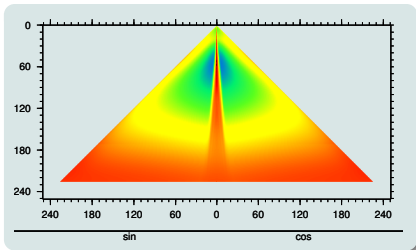
GOCE-only models compared to EGM08: 2, 6, 12 months data



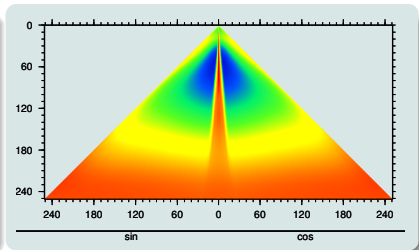
solid: degree error variance from difference to EGM08, **dashed:** degree error variance from formal errors

Accuracies of gravity coefficients:

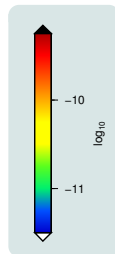
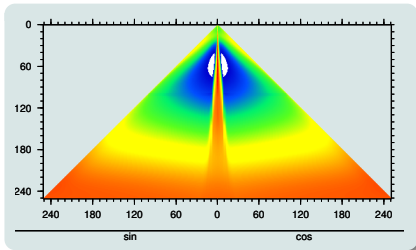
2 months:



6 months:

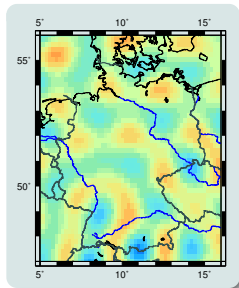


12 months:



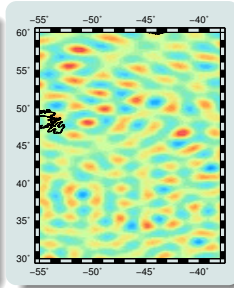
Anomalies compared to EGM08 (d/o 200, m/s^2) on local scale (12 months data):

Germany:



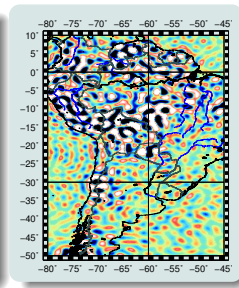
min : -5.3 mgal
 max : $+3.3$ mgal
 rms : $+1.4$ mgal
 $\bar{\sigma}_g$: $+1.4$ mgal

Ocean:

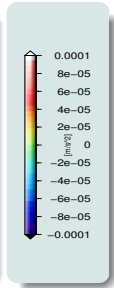


min : -5.0 mgal
 max : $+5.4$ mgal
 rms : $+1.5$ mgal
 $\bar{\sigma}_g$: $+1.4$ mgal

South America:

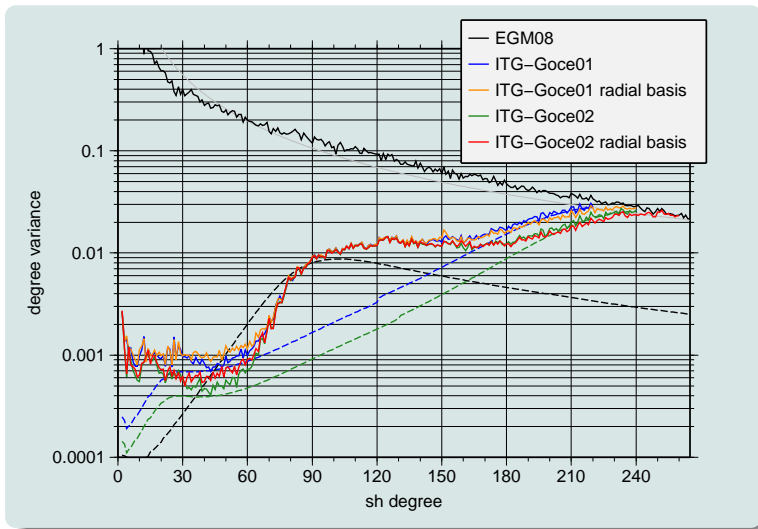


min : -65.1 mgal
 max : $+55.4$ mgal
 rms : $+7.1$ mgal
 $\bar{\sigma}_g$: $+1.7$ mgal



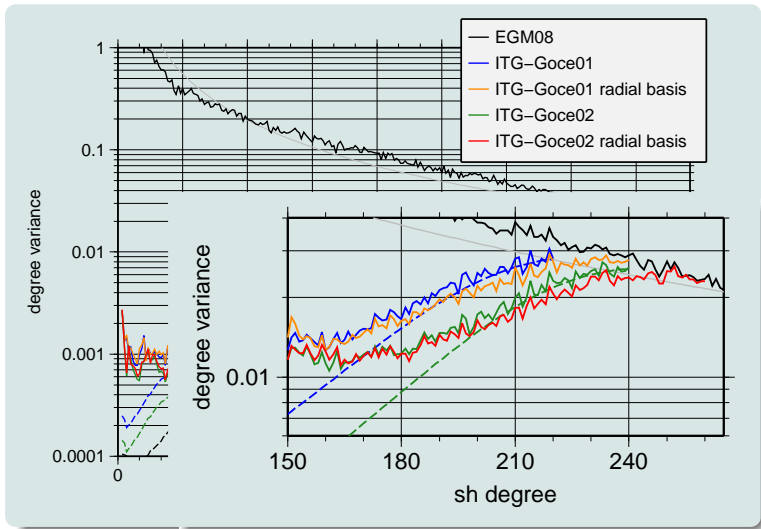
diff.EGM08
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 var.prop.

GOCE-only models compared to EGM08:



solid: degree error variance from difference to EGM08, **dashed:** degree error variance from formal errors

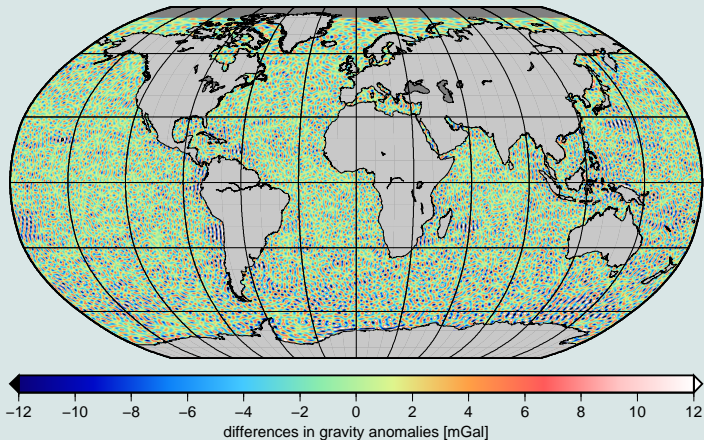
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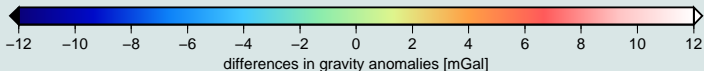
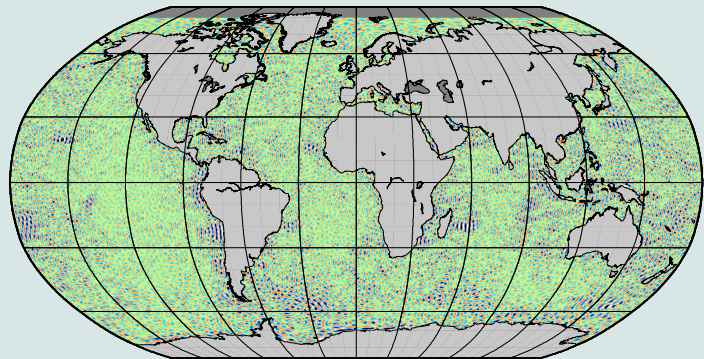
2 months anomalies compared to EGM08 (d/o 200, m/s^2):

(min=-31.2019, max=31.9712, avg=2.90329, rms=3.74177)



2 months refined anomalies compared to EGM08 (d/o 200, m/s^2)

(min=-27.4435, max=30.0586, avg=2.52967, rms=3.31923)



Summary:

- ▶ consistent gravity field solutions from all three approaches
- ▶ improvements with 12 months data
- ▶ EGM08 improvement d/o 60-180
- ▶ improvements with regional refinement

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Outlook:

- ▶ data up to at least end of 2012
- ▶ ESA reprocesses L1b gravity gradients
- ▶ first promising results

GOCE-only models compared to GOCO02s:

2 months, 2 months reprocessed

