

Estimation of phase center variation and its effect on precise orbit determination

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G-07 High Precision GNSS

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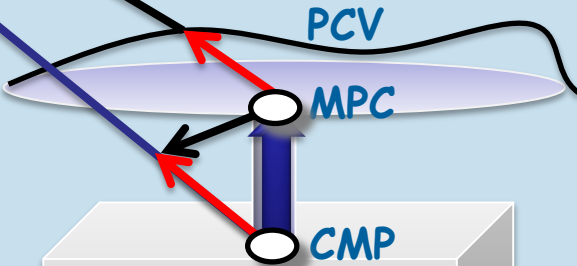
- Definition of phase center offset (PCO) and its variation (PCV)
- Modelling of Phase Center Variation (PCV)
- Geometrical Precise Orbit Determination (GPOD)
- GPOD and PCV Results
 - ✓ GRACE
 - ✓ GOCE
- Conclusion

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GNSS Satellite

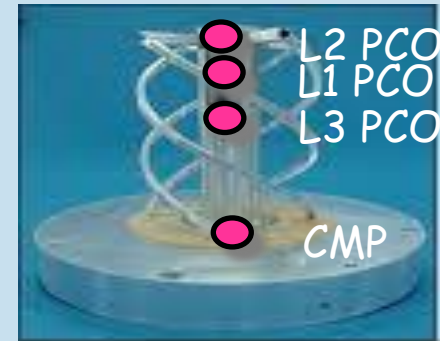


GNSS Antenna



Benchmark/
GNSS station

- **CMP** (center of instrument's mounting plane):
frequency independent, instrument offset,
defined in the satellite (LEO) reference frame
- **PCO** (Phase center offset): **frequency dependent**, defined w.r.t **CMP** in the antenna reference frame (ARF)
- **PCV** (Phase center variations): **frequency dependent**, defined w.r.t **PCO** in the antenna reference frame (ARF), varying with the **direction** (azimuth and zenith) of incoming GNSS signal



GOCE Antenna
Credit: ESA

Carrier phase observation equation:

$$\Phi_{r,i}^s(t) = \rho_r^s(t) + c\delta t_r(t) - I_r^s(t) + T_r^s(t) + \lambda_i A_{r,i}^{s_1} + O_{r,i}^s(t) + \varepsilon_{r,i}^s(t)$$

Phase center offset and variation can be

defined as:

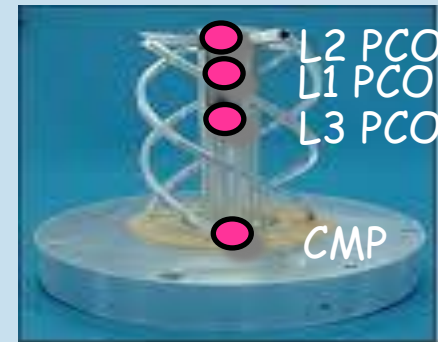
$$O_{r,i}^s(t) = \mathbf{r}_0 \cdot \mathbf{e}_r^s + \Delta\Psi(\alpha, z)$$

According to Rothacher et al. (1995), phase center corrections

(PCO and PCV) have some inherent degrees of freedom:

$$\mathbf{r}'_0 \Rightarrow \mathbf{r}_0 + \Delta\mathbf{r}_0$$

$$\Delta\Psi'(\alpha, z) \Rightarrow \Delta\Psi(\alpha, z) - \Delta\mathbf{r}_0 \cdot \mathbf{e}_r^s + \Delta\Delta\Psi$$



GOCE Antenna

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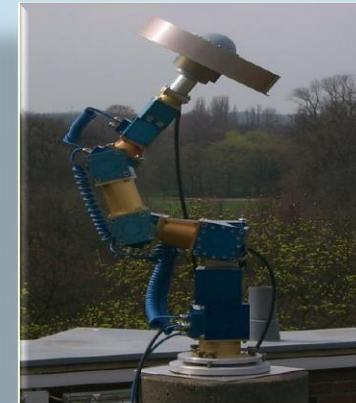
$$\Delta\Psi'(\alpha, z) \Rightarrow \Delta\Psi(\alpha, z) - \Delta\mathbf{r}_0 \cdot \mathbf{e}_r^s + \Delta\Delta\Psi$$

$\Delta\mathbf{r}_0, \Delta\Psi_0$: arbitrary location of mean phase center and arbitrary phase offset for all directions

To avoid singularity we assume:

- ✓ Summation over all azimuth and zenith angles to zero (zero mean)
- ✓ Bore-sight to zero
- ✓ Other constrains...

- Anechoic Test Chamber (Chamber measurements, relative PCO and PCV)
- Absolute phase center offset and variation based on robot calibration
- Empirical estimation of PCV based on GNSS carrier phase residuals (in-flight calibration)



PCV can be modelled based on spherical harmonic coefficients as:

$$\Delta\Psi(\alpha, z) = \sum_{n=0}^{n_{\max}} \sum_{m=0}^n c_{nm} C_{nm}(\alpha, z) + s_{nm} S_{nm}(\alpha, z)$$

with

$$C_{nm}(\alpha, z) = \bar{P}_{nm}(\cos z) \cos m\alpha$$

$$S_{nm}(\alpha, z) = \bar{P}_{nm}(\cos z) \sin m\alpha$$

With unknowns as $(n_{\max} = 8 - 10)$: c_{nm}, s_{nm}

- ✓ To prevent the **normal equation systems** from becoming **singular**, a **priori constraint** has to be added on each parameter (because of arbitrary phase shift!)
- ✓ With least squares method, **the unknown parameters** can be estimated based on post-fit GNSS **carrier phase residuals**.

- ✓ After empirically estimation of **spherical harmonics coefficients**, the antenna PCO and PCV map can be generated as **tabular correctios** (e.g. **ANTEX**, Antenna Exchange Format).
- ✓ The generated antenna PCO and PCV map can be used to future GNSS estimation procedure as a systematical error.



GNSS residual approach compared to other methods:

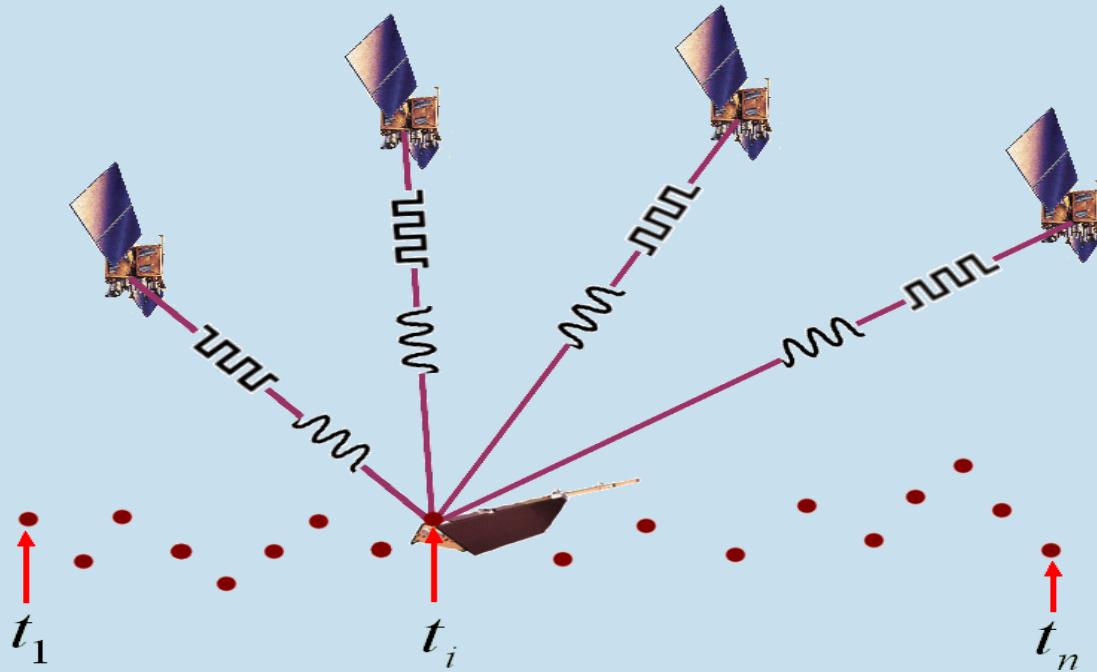
Advantages

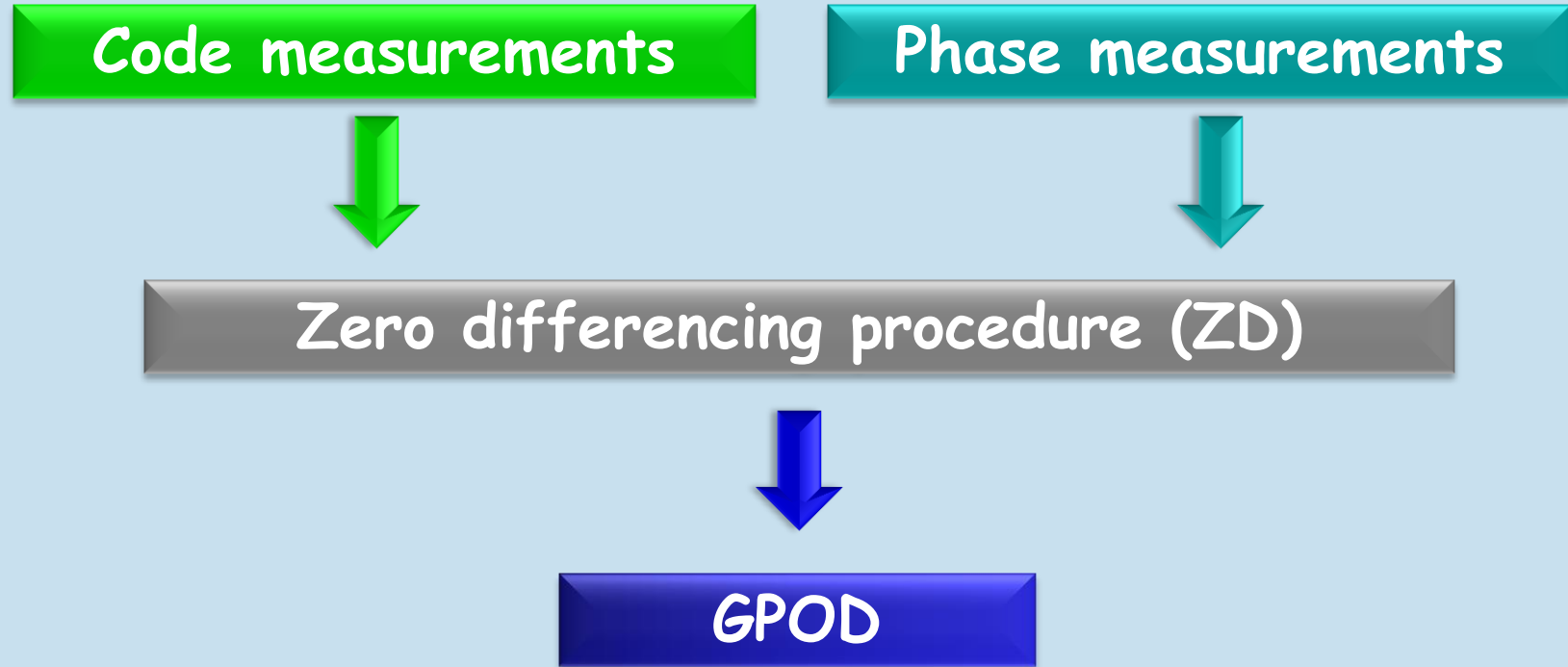
- ✓ Smaller effort
- ✓ A large number of GNSS antennas in a short time period
- ✓ A small accurate network with fixed positions can be used to calibrate and determine antenna PCO and PCV map

Disadvantages

- ✓ Some iterations are needed to absorb all residuals and estimate final antenna map
- ✓ It depends on the data availability and data volume!







Zero Difference

Only connection between LEO and GPS satellites

Geometrical

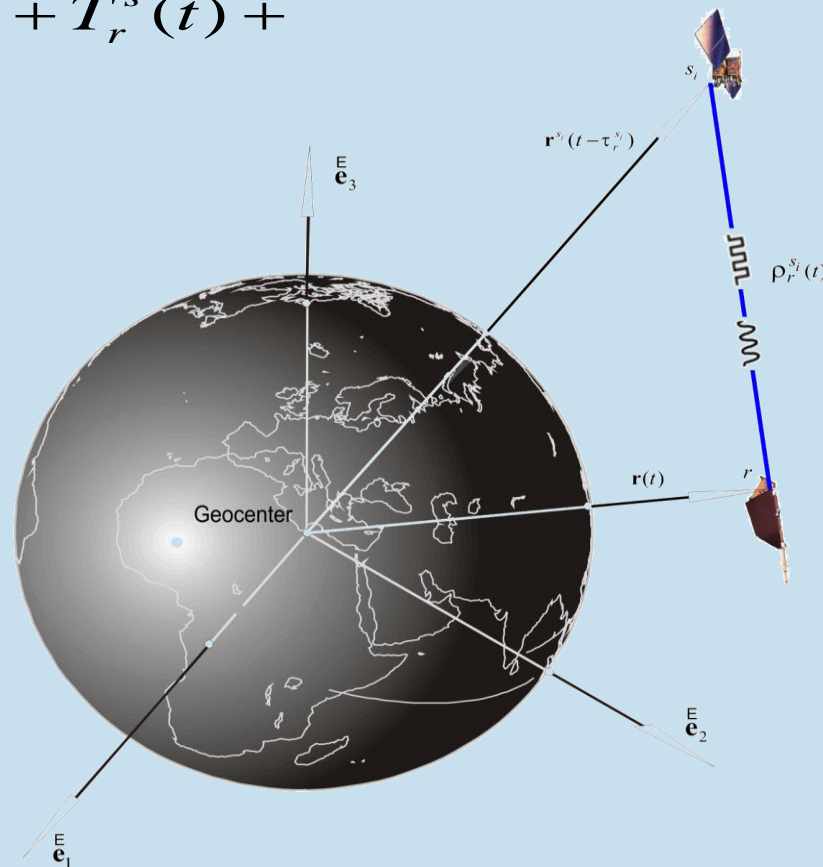
Only pure geometrical relations between LEO and the GPS satellites have to be used, no force models and no constraints

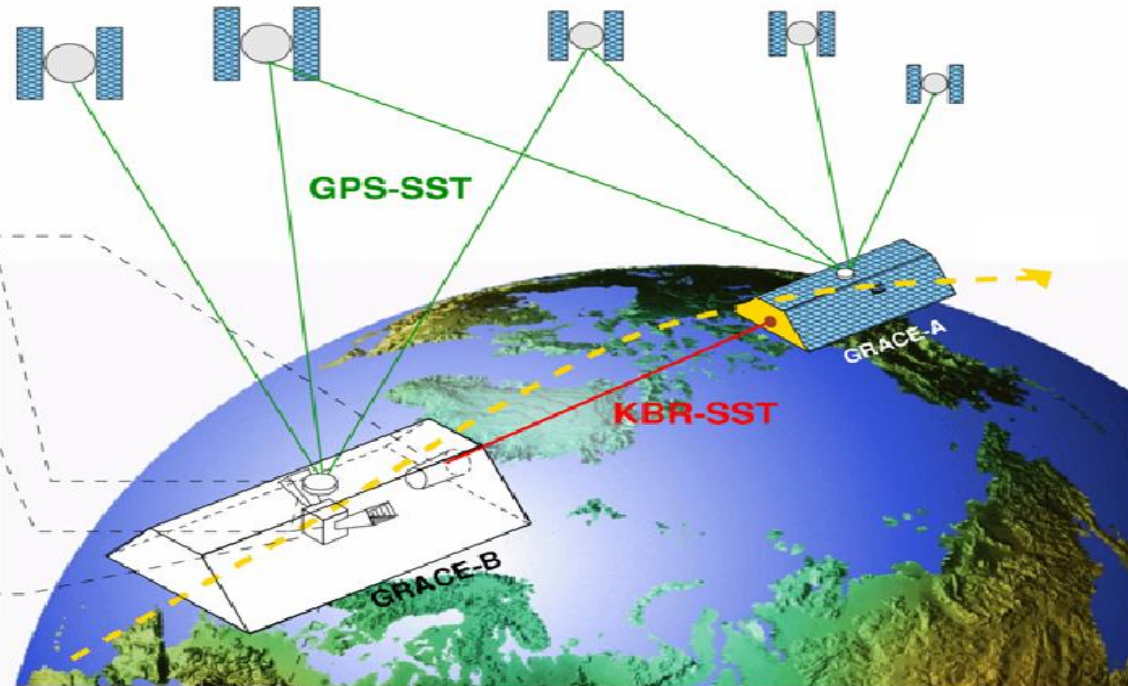
Precise

Consideration of all effects on SST observations, using precise GNSS ephemerides and clocks

$$\Phi_{r,i}^s(t) = \rho_r^s(t) + c\delta t_r(t) - I_r^s(t) + T_r^s(t) + \lambda_i A_{r,i}^{s_1} + O_{r,i}^s(t) + \varepsilon_{r,i}^s(t)$$

- No tropospheric effect at LEO altitude (~250-1000 km)
- First order ionospheric effect eliminated with Ion-free linear combination
- Ambiguity term cannot be solved as integer (real)!
- GPS precise orbits (at 15 minutes) and clocks at 30 sec

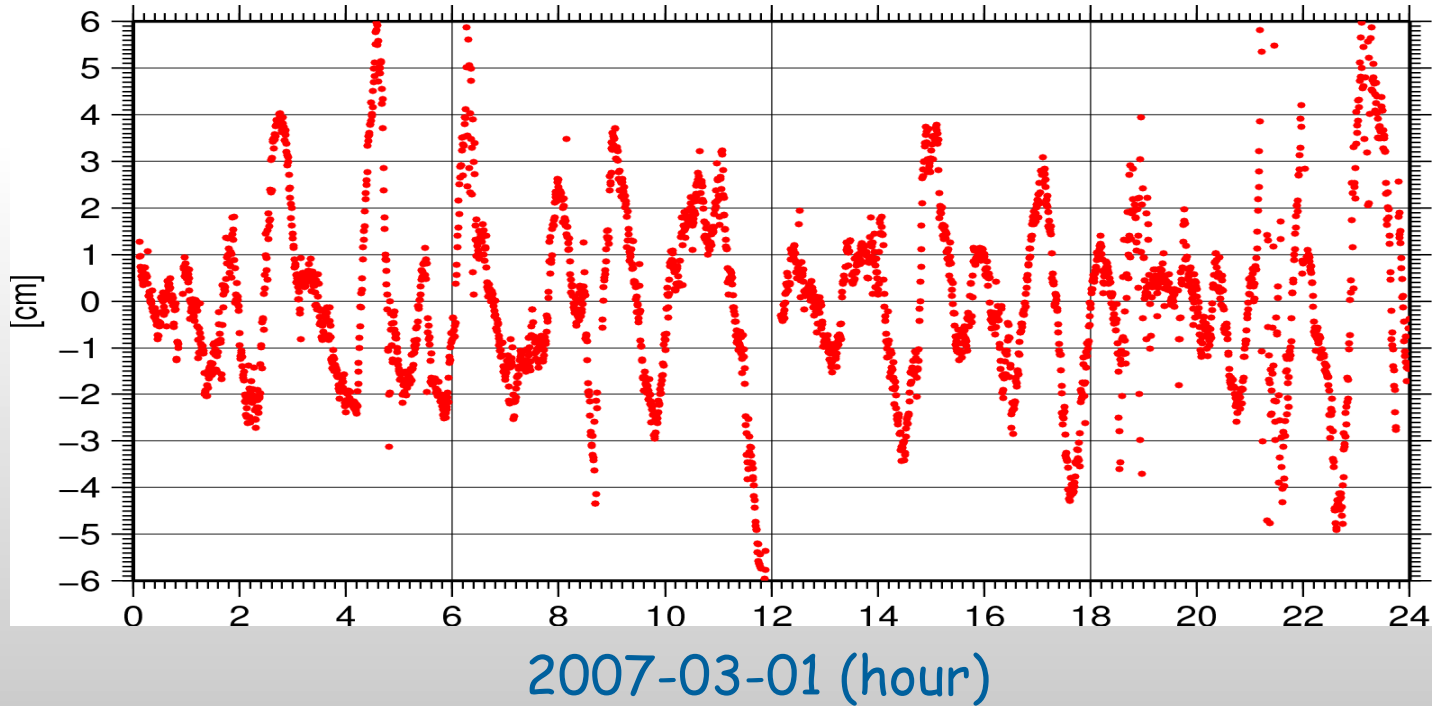




Start: 17 March 2002
Altitude: 500 km
Inclination: 89.5 deg

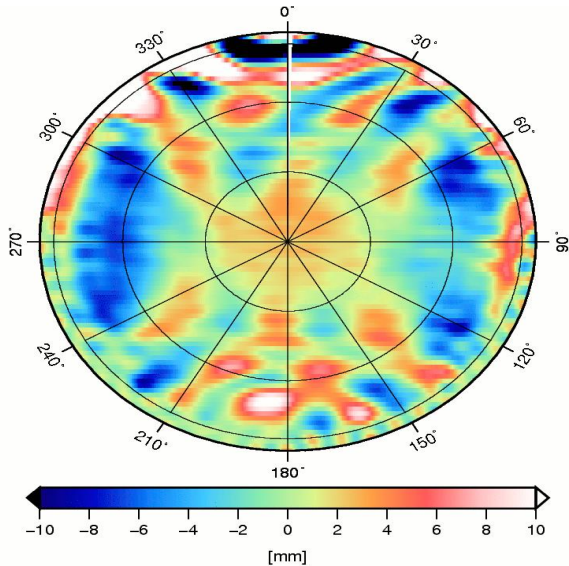
Excentricity: 0.002
Low-low SST: 220 km

Comparison of GPS derived geometrical orbits and K-Band ranges

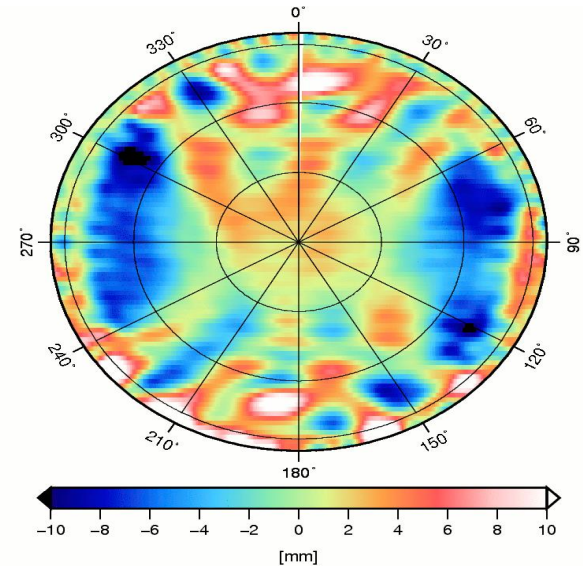


- More than 85 months of GNSS GRACE data have been used to estimated geometrical precise orbit of twin satellites
- Based on spherical harmonics, the phase center variations for twin satellites have been estimated as:

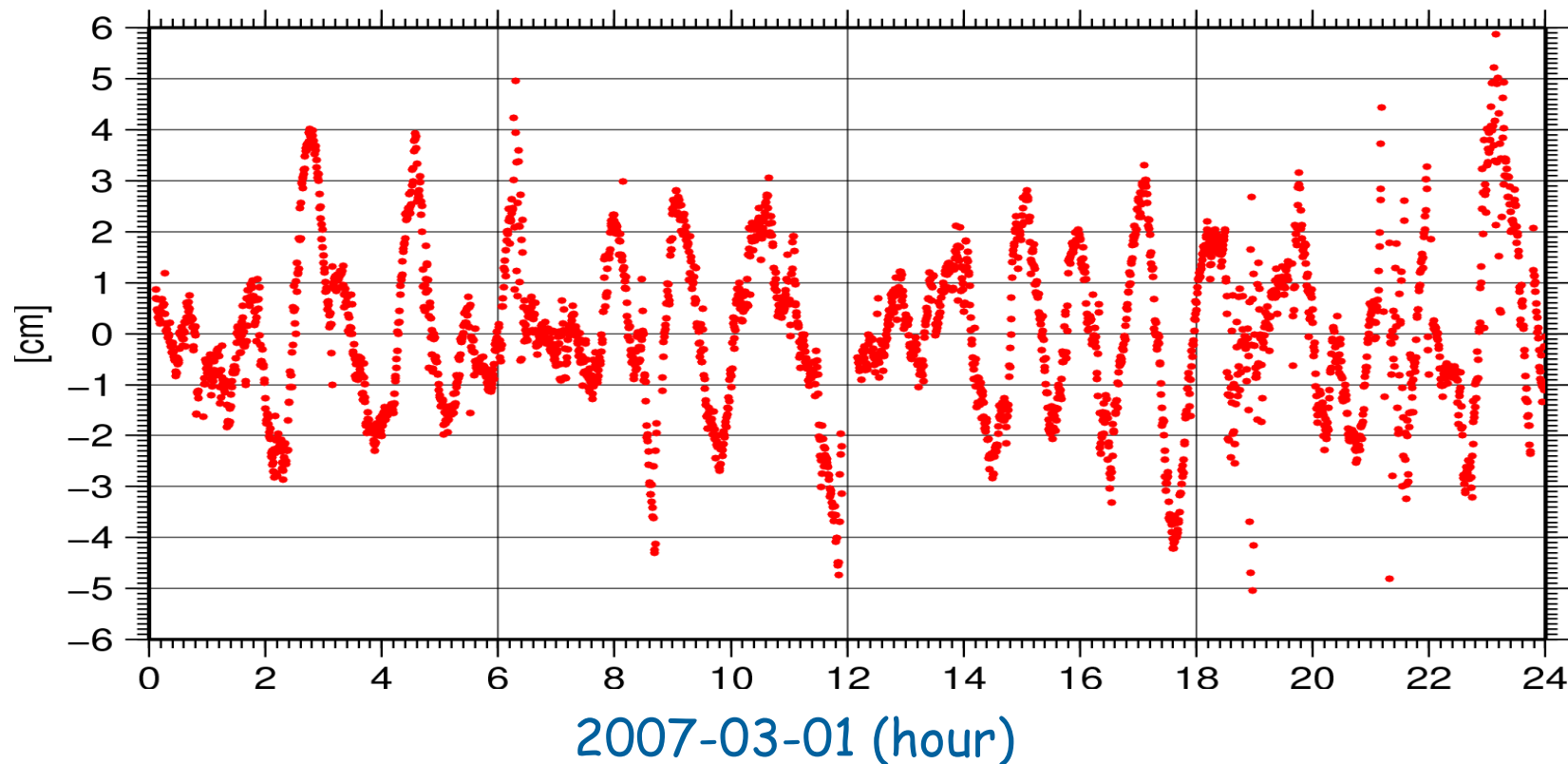
GRACE A

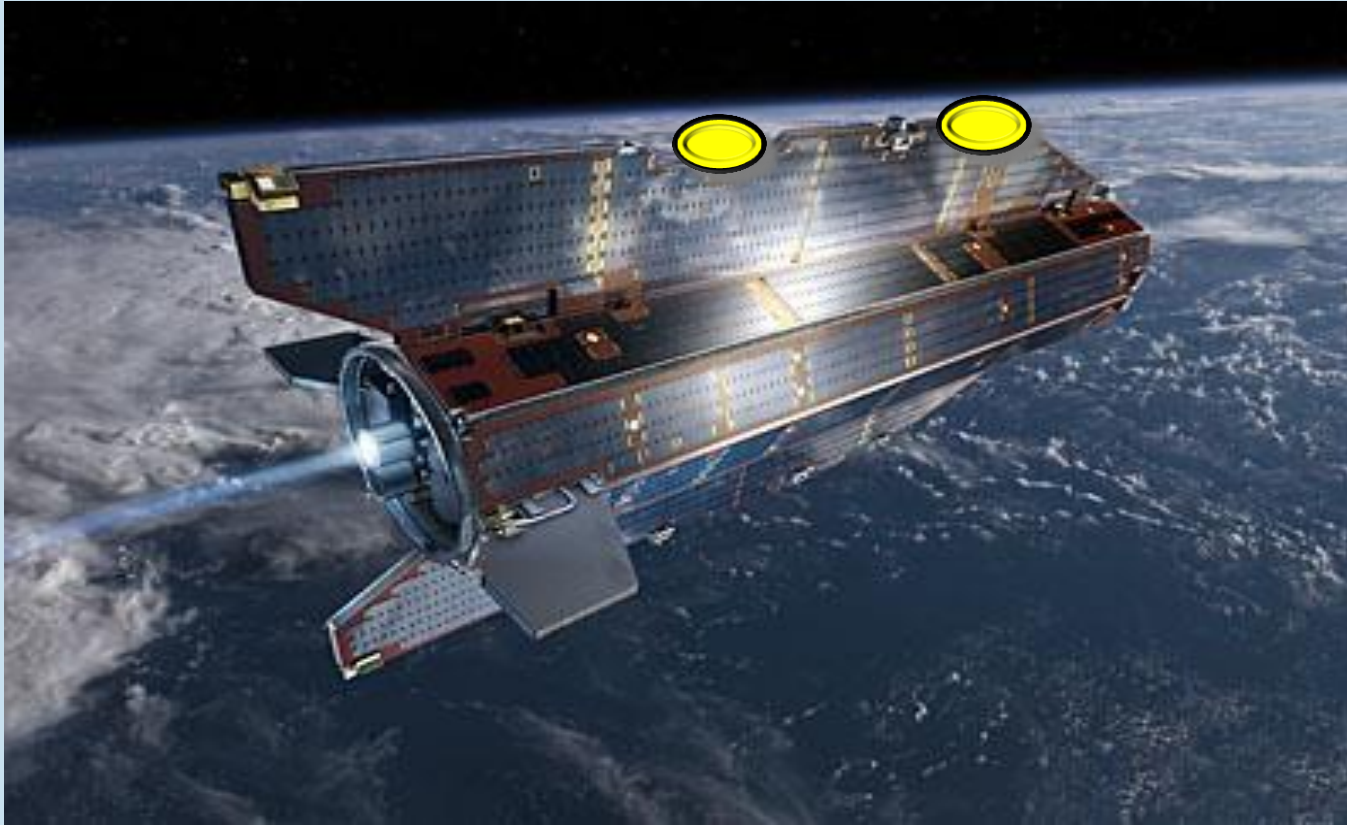


GRACE B



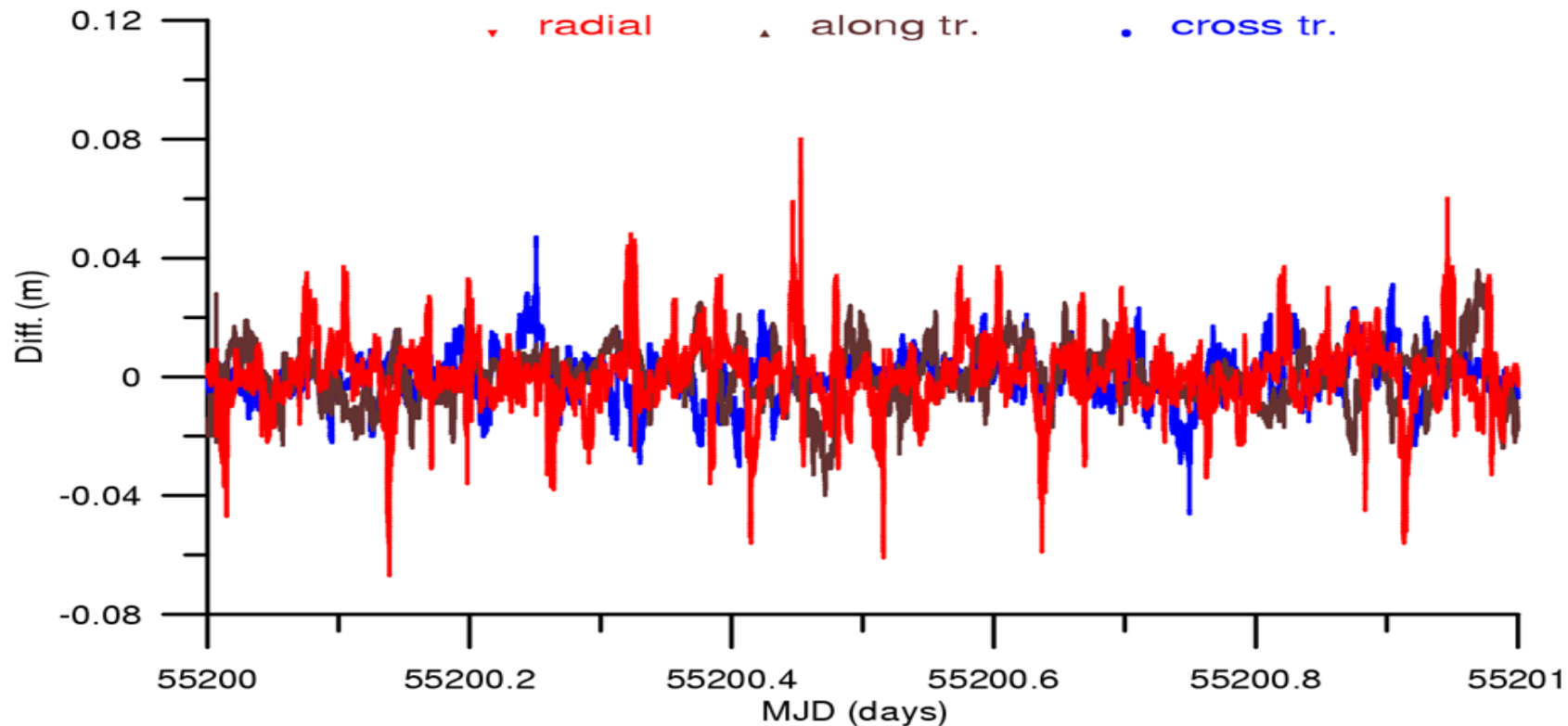
Comparison of GPS derived geometrical orbits and K-Band ranges



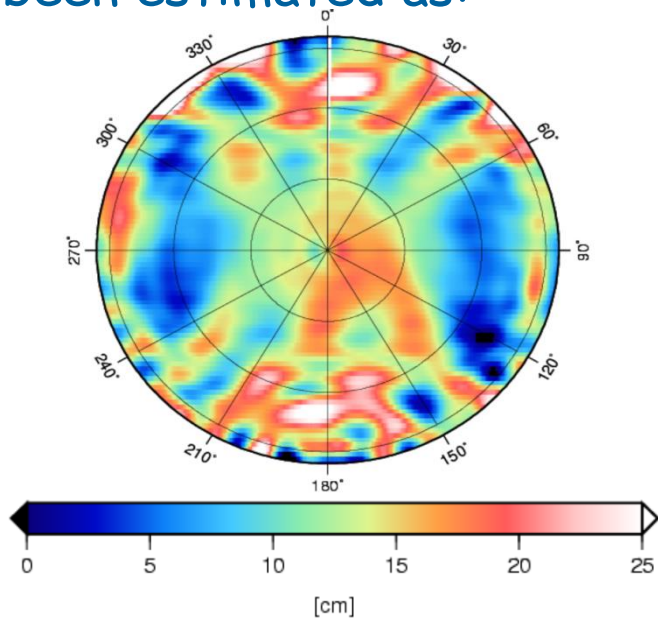


- Start: 17 Mar. 2009
- Altitude: 254 km
- Sun Synchronize
- Inclination: 96.5 deg

Comparison of GPS derived geometrical POD and PSO orbit



- More than 72 days of GNSS GOCE data have been used to estimated geometrical precise orbit of GOCE satellite
- Based on GNSS residuals, the phase center variation of GOCE has been estimated as:



=>Estimated PCV should be used as a systematical effect on GPOD estimation procedure.

Comparison of GPS derived geometrical POD and PSO orbit

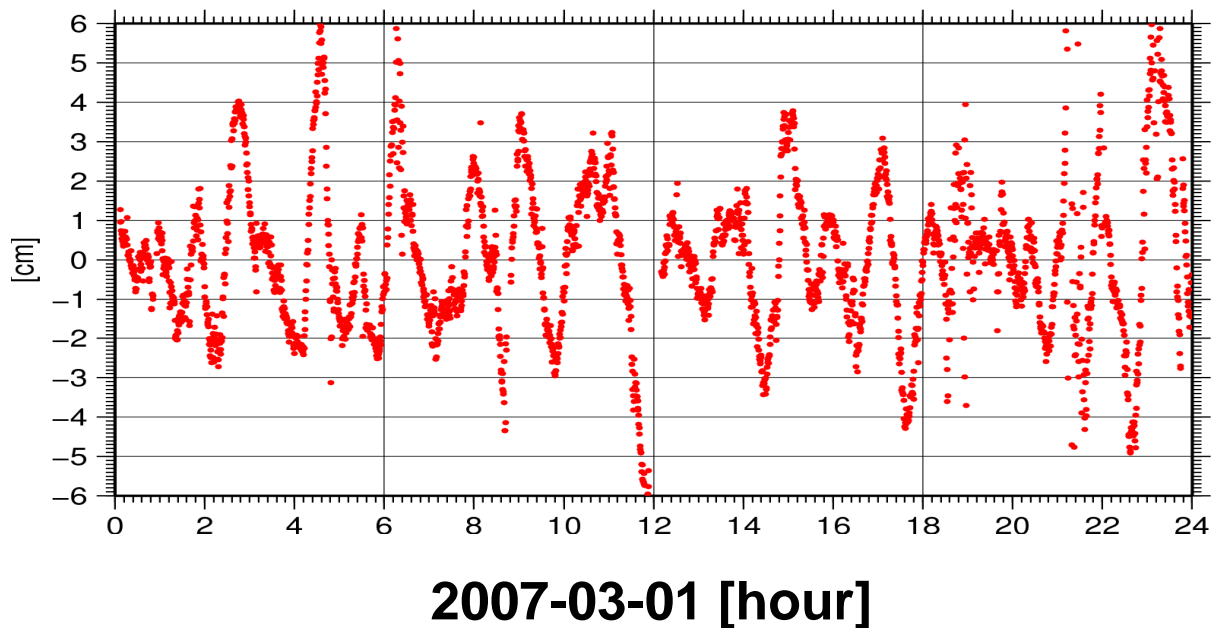


- ✓ GNSS-LEO satellites configuration and geometrical strength play an important role in Geometrical POD, subsequently in PCV
- ✓ PCV based on GNSS carrier phase observation residuals successfully implemented and affects Geometrical POD
- ✓ To estimate reliable phase center variation, long period of GNSS data should be used as pseudo-observations.
- ✓ No gravity field and no force models have been used in the Geometrical POD. Therefore, it can be directly used to recover of the Earth's gravity field.

**Thank you
for your attention**

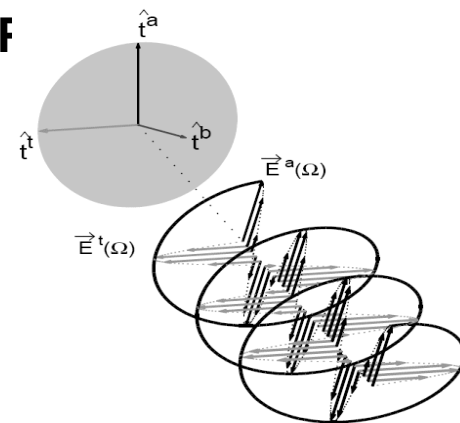


Comparison of GPS derived kinematic orbits - K-Band ranges



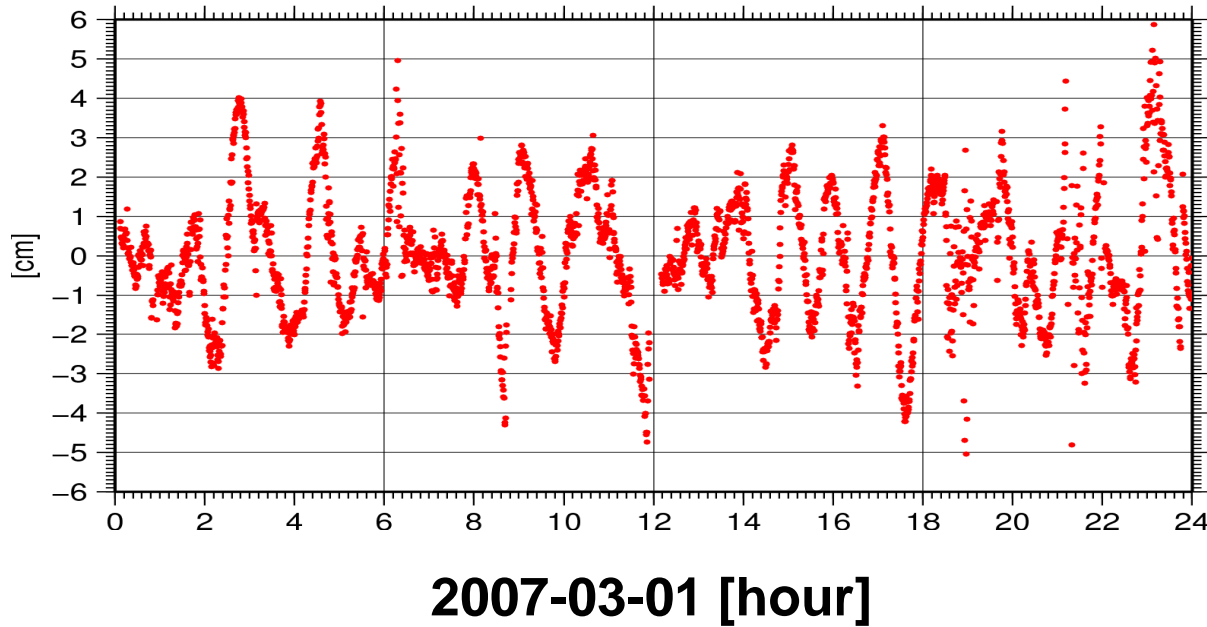
•Improvements in the GPS processing

- F



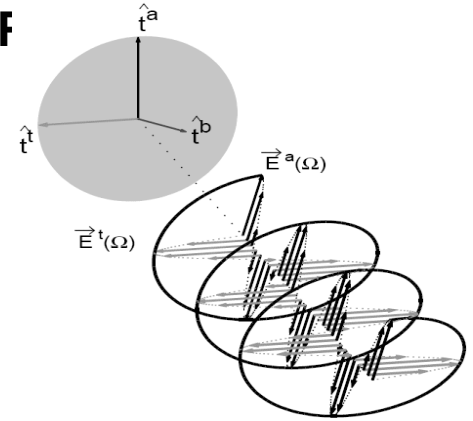
G. Beyerle 2008

Comparison of GPS derived kinematic orbits - K-Band ranges



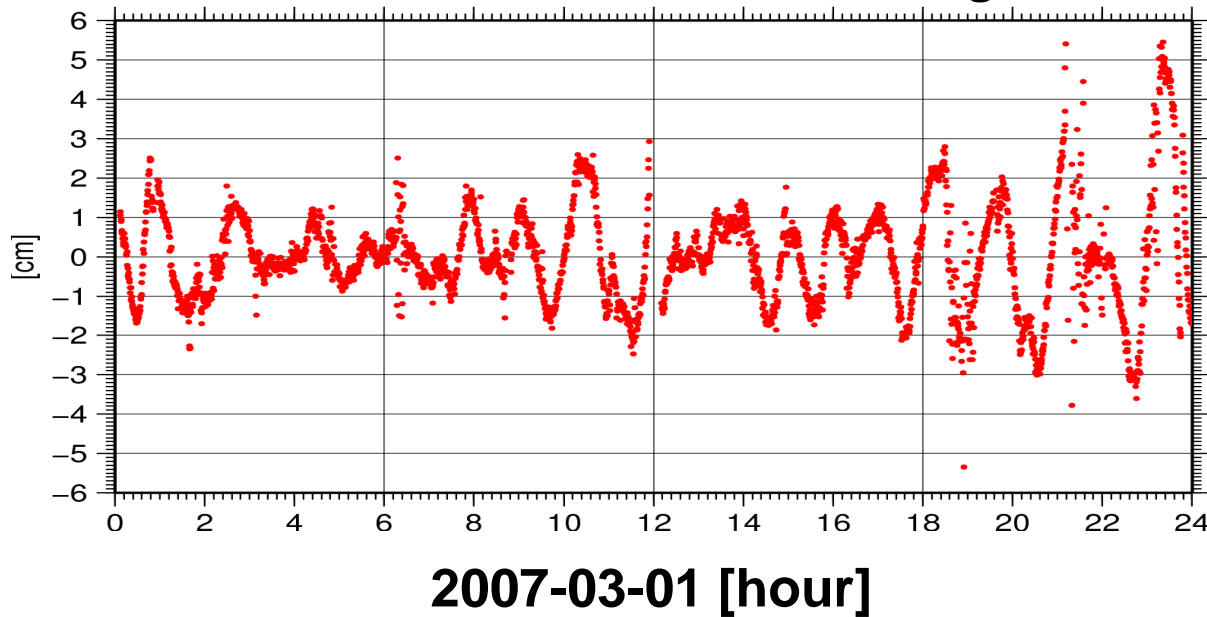
Improvements in the GPS processing

- F



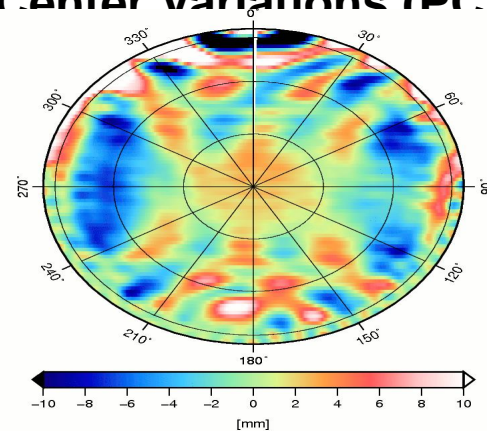
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Comparison of GPS derived kinematic orbits - K-Band ranges

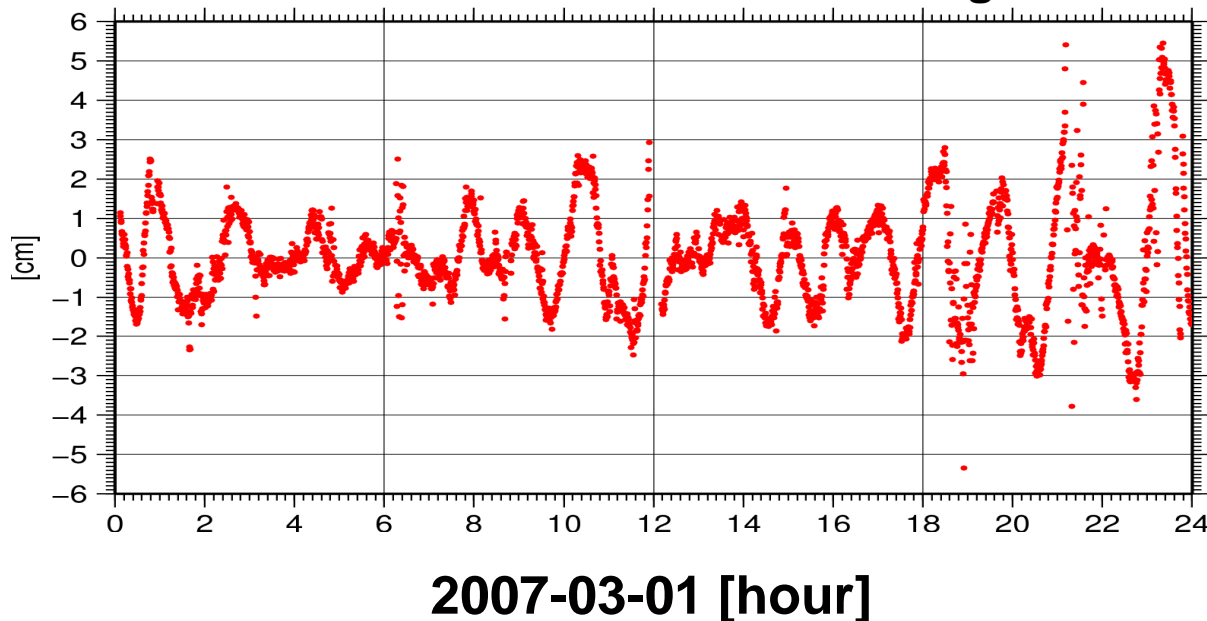


Improvements in the GPS processing

- Phase wind-up
- Empirical Phase Center Variations (PCV)



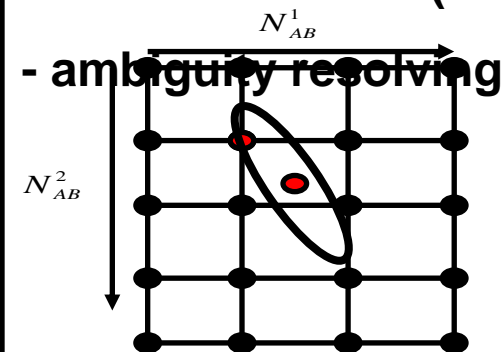
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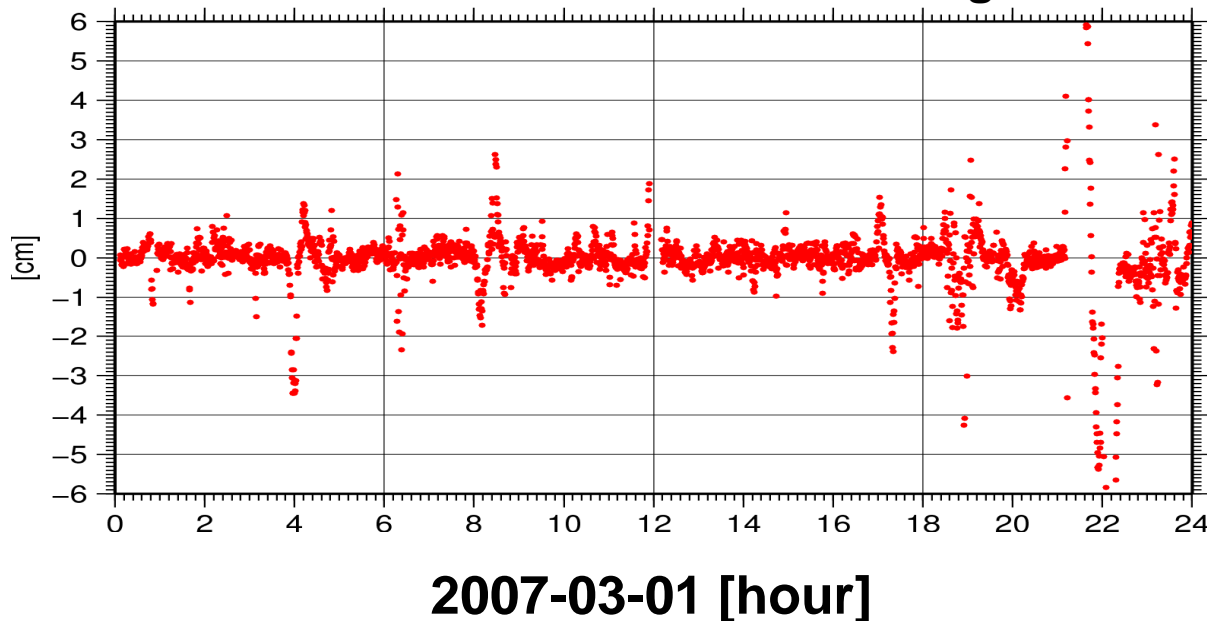
Improvements in the GPS processing

- Phase wind-up
- Empirical Phase Center Variations (PCV)

- ambiguity resolving



Comparison of GPS derived kinematic orbits - K-Band ranges



Improvements in the GPS processing

- Phase wind-up
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